## Data Sheet

Programmable Multi-transducer (MODBUS Rs485 Communication)


Fig. 1

## Application

for the measurement of electrical variables in heavy current power systems
RISH Ducer M01 (Fig. 1) is a programmable transducer with RS
485 bus interface (MODBUS) ${ }^{\circledR}$. It supervises several parameter of an electrical power system simultaneously.
The RS 485 interface enables the user to determine the number variables to be supervised (up to the maximum available). The levels of all internal counters that have been configured (max. 4) can also viewed. Provision is made for programming the RISH Ducer M01 via the bus. A standard EIA 485 interface can be used. The transducers are also equipped with an RS 232 serial interface to which a PC with the corresponding software can be connected for programming or accessing and executing useful ancillary functions.
This interface is needed for bus operation to configure the device address, the Baud rate and possibly increasing the message waiting time (if the master is too slow) defined in the MODBUS ${ }^{\circledR}$ protocol.
The usual methods of connection, the types of measured variables, their ratings and the type of internal energy/metering are the main parameters that can be programmed.
The ancillary functions include a power system check and a facility for printing nameplates.
The transducer fulfils all the essential requirements and regulations concerning electromagnetic compatibility (EMC) and safety (IEC 1010 resp. EN 61010 ). It was developed and is manufactured and tested in strict accordance with the quality assurance standard ISO 9001.

## Features

- Simultaneous measurement of several variables of a heavycurrent power system / full supervision of an asymmetrically loaded four-wire power system, rated current 1 to 6 A , rated voltage 57 to 400 V (phase to neutral) or 100 to 693 V (phase-to-phase)
- For all heavy-current power system variables
- Input voltage up to 693 V (phase-to-phase)
- Universal analogue outputs (programmable)
- Transfer of data via MODBUS ${ }^{\circledR}$ interface
- High accuracy: U/I 0.2\%, (under reference conditions)
- Universal digital outputs (meter transmitter, limits)
- 4 integrated energy meters, storage every each 203 s, storage for : 20 years
- Windows software with password protection for programming, data analysis, power system status simulation, acquisition of meter data and making settings
- DC-, AC- power pack with wide power supply tolerance /universal Provision for either snapping the transducer onto top - hat rails or securing it with screws to a wall or panel

| Measured variables |  | Types |
| :---: | :---: | :---: |
| Current, Voltage (rms), active/reactive/apparent power $\operatorname{Cos} \varphi, \sin \varphi$, power factor RMS value of the current with wire setting range (bimetal measuring function) Slave pointer function for the measurement of the RMS value IB Frequency Average value of the currents with sign of the active power (power symbol only) | Without analogue outputs, with bus interface RS 485 (MODBUS) | Ducer M |
|  | 4 analogue and bus interface RS 485 (MODBUS) | Ducer M |
|  | 2 analogue and 4 digital outputs | Ducer M2 |
|  | 4 analogue and 2 digital outputs see Data sheet | Ducer M4 |
|  | Data bus LON see Data Sheet M00 | Ducer M00 |



1 = Input transformer
6 = Electrical insulation
2 = Multiplexer
7 = Programming interface RS-232
3 = Latching stage
8 = Bus RS 485 (MODBUS)
4 = A/D converter
9 = Power supply

5 = Microprocessor
Fig. 2. Block diagram.
The RS 485 interface of the M01 is galvanically isolated from all other circuits. For an optimal data transmission the devices are connected via a 3 - wire cable, consisting of a twisted pair cable (for data lines) and a shield. There is no termination required. A shield both prevents the coupling of external noise to the bus and limits emissions from the bus. The shield must be connected to solid ground.
You can connect up to 32 members to the bus (including master).
Basically devices of different manufacturers can be connected to the bus, if they use the standard MODBUS ${ }^{\circledR}$ protocol. Devices without galvanically isolated bus interface are not allowed to be connected to the shield.
The optimal topology for the bus is the daisy chain connection from node 1 to node 2 to node n . The bus must form a single continuous path, \& the nodes in the middle of the bus must have short stubs. Longer stubs would have a negative impact on signal quality (reflection at the end). A star or even ring topology is not allowed.


Fig. 4
There is no bus termination required due to low data rate. If you got problems when using long cables you can terminate the bus at both ends with the characteristic impedance of the cable (normally about $120 \Omega$ ). Interface convertors RS232 $\Leftrightarrow$ RS 485 or RS564 interface cards often have a built-in termination network which can be connected to the bus. The second impedance then can be connected directly between the bus terminals of the device far most.

Fig. 4 shows the connection of transducers M01 to the MODBUS. The RS 485 interface can be realized by means of PC built - in interface cards or interface converters. Both is shown using i.e. the interfaces 13601 and 86201 of W \& T (Wiesemann \& Theis $\mathrm{GmbH})$. They are configured for a 2 -wire application with automatic control of data direction. These interfaces provide a galvanical isolation and a built-in termination network.

## Important:

- Each device connected to the bus must have a unique address
- All devices must be adjusted to the same baudrate.


## Symbols and their meaning

| Symbols | Meaning |
| :---: | :---: |
| X | Measured variable |
| X0 | Lower limit of the measured variable |
| X1 | Break point of the measured variable |
| X2 | Upper limit of the measured variable |
| Y | Output variable |
| Y0 | Lower limit of the output variable |
| Y1 | Break point of the output variable |
| Y2 | Upper limit of the output variable |
| U | Input voltage |
| Ur | Rated value of the input voltage |
| U 12 | Phase-to-phase voltage L1-L2 |
| U 23 | Phase-to-phase voltage L2-L3 |
| U 31 | Phase-to-phase voltage L3-L1 |
| U1N | Phase-to-neutral voltage L1-N |
| U2N | Phase-to-neutral voltage L2-N |
| U3N | Phase-to-neutral voltage L3-N |
| UM | Average value of the voltages |
|  | (U1N + U2N + U3N) / 3 |
| I | Input current |
| 11 | AC current L1 |
| 12 | AC current L2 |
| 13 | AC current L3 |
| Ir | Rated value of the input current |
| IM | Average value of the currents ( $11+12+13$ )/3 |
| IMS | Average value of the currents and sign of the active power (P) |
| IB | RMS value of the current with wire setting range (bimetal measuring function) |
| IBT | Response time for IB |
| BS | Slave pointer function for the measurement of the RMS value IB |
| BST | Response time for BS |
| $\varphi$ | Phase-shift between current and voltage |
| F | Frequency of the input variable |
| Fn | Rated frequency |
| P | Active power of the system P=P1+P2 + P3 |
| P1 | Active power phase 1 (phase-to-neutral L1-N) |
| P2 | Active power phase 2 (phase-to-neutral L2-N) |
| P3 | Active power phase 3 (phase-to-neutral L3-N) |


| Symbols | Meaning |
| :--- | :--- |
| Q | Reactive power of the system Q = Q1+ Q2 + Q3 |
| Q1 | Reactive power phase 1 (phase-to-neutral L1-N) |
| Q2 | Reactive power phase 2 (phase-to-neutral L2-N) |
| Q3 | Reactive power phase 3 (phase-to-neutral L3-N) |
| S | Apparent power of the system <br> $\mathrm{S}=\sqrt{I_{1}{ }^{2}+\mathrm{I}_{2}{ }^{2} \mathrm{I}_{3}{ }^{2}} \cdot \sqrt{\mathrm{U}_{1}{ }^{2}+\mathrm{U}_{2}{ }^{2}+\mathrm{U}_{3}{ }^{2}}$ |
| S1 | Apparent power phase 1 <br> (phase-to-neutral L1-N) |
| S2 | Apparent power phase 2 <br> (phase-to-neutral L2-N) |
| S3 | Apparent power phase 3 <br> (phase-to-neutral L3-N) |
| Sr | Rated value of the apparent power of the system |
| PF | Active power factor cos $\varphi$ =P/S |
| PF1 | Active power factor phase1 P1/S1 |
| PF2 | Active power factor phase2 P2/S2 |
| PF3 | Active power factor phase3 P3/S3 |
| QF | Reactive power factor sin j =Q/S |
| QF1 | Reactive power factor phase1 Q1/S1 |
| QF2 | Reactive power factor phase2 Q2/S2 |
| QF3 | Reactive power factor phase3 Q3/S3 |
| LF | Power factor of the system <br> LF = sgnQ (1- PF ) |
| LF1 | Power factor phase 1 <br> sgnQ1 (1 - PF1 ) |
| LF2 | Power factor phase 2 <br> sgnQ2 (1 - PF2 ) |
| LF3 | Power factor phase 3 <br> sgnQ3 (1 - PF3 ) |
| H | Power supply |
| Hn | Rated value of the power supply |
| CT | c.t. ratio |
| VT | v.t. ratio |

## Technical Data

## Input

Input variables
Measuring ranges
Waveform
Rated frequency
Own consumption [VA]
see Table 3 and 4
see Table 3 and 4
Sinusoidal
50... $60 \mathrm{~Hz} ; 162 / 3 \mathrm{~Hz}$

Voltage circuit: $\leq \mathrm{U}^{2} / 400 \mathrm{k}$ OHM
Condition:
Characteristic XH 01...XH10
Current circuit: $\leq 120.01$ OHM

Continuous thermal ratings of inputs

| Current circuit | $10 \mathrm{~A}$ | 400 V <br> single-phase <br> AC system <br> 693 V <br> three-phase system |
| :---: | :---: | :---: |
| Voltage circuit | $\begin{aligned} & 480 \mathrm{~V} \\ & 831 \mathrm{~V} \end{aligned}$ | single-phase AC system three-phase system |

Short-time thermal rating of inputs

| Input <br> variable | Number of <br> inputs | Duration <br> of <br> overload | Intervall <br> between two <br> overloads |
| :--- | :--- | :---: | :---: |
| Current circuit | 400 V single-phase AC system <br> 693 V three-phase system |  |  |
| 100 A | 5 | 3 s | 5 min. |
| 250 A | 1 | 1 s | 1 hour |
| Voltage circuit | $1 \mathrm{~A}, 2 \mathrm{~A}, 5 \mathrm{~A}$ |  |  |
| Single-phase <br> AC system <br> 600 V <br> $\mathrm{H}_{\text {intern }}: 1.5 \mathrm{Ur}$ | 10 | 10 s | 10 min. |
| Three-phase <br> system <br> 1040 V <br> $\mathrm{H}_{\text {intern }}: 1.5 \mathrm{Ur}$ | 10 | 10 s | 10 s |

MODBUS ${ }^{\circledR}$ (Bus interface RS-485)
Terminals
Screw terminals, terminals 23, 24, 25 and 26
Connecting cable
Max. distance
Baudrate
Number of bus
stations Screened twisted pair Approx. 1200 m (approx. 4000 ft .) 1200 ... 9600 Bd (programmable)

Dummy load

32 (including master) Not required


MODBUS $^{\circledR}$ is a registered trademark of the Schneider Automation Inc.

## System response

Accuracy class
Duration of the
measurement cycle

Response time

## Reference conditions

Ambient temperature
Pre-conditioning
Input variable
Power supply
Active/reactive factor
Frequency
Waveform
Output load
Miscellaneous
0.2 resp. 0.4 at applications with phase-shift

Approx. 0.5 to 1.2 s at 50 Hz , depending on measured variable and programming
1 ... 2 times the measurement cycle
$15 . . .30^{\circ} \mathrm{C}$
30 min. acc. to DIN EN 60688
Rated useful range
$\mathrm{H}=\mathrm{Hn}+1 \%$
$\cos \phi=1$ resp. $\sin \phi=1$
50 ... $60 \mathrm{~Hz}, 162 / 3 \mathrm{~Hz}$
Sinusoidal, form factor 1.1107
DC current output:
EN 60688

Influencing quantities and permissible variations
Acc. to EN 60688

## Power Supply $\rightarrow 0$

DC-, AC - power pack (DC and $50 \ldots 60 \mathrm{~Hz}$ )
Table 1: Rated voltages and tolerances

| Rated voltage $\mathrm{U}_{N}$ | Tolerance |
| :--- | :--- |
| $24 \ldots 60 \mathrm{~V} \mathrm{DC/AC}$ | $\mathrm{DC}-15 \ldots+33 \%$ |
| $85 \ldots 230 \mathrm{~V} \mathrm{DC/AC}$ | $\mathrm{AC} \pm 10 \%$ |

Programming connector on transducer

Interface:
DSUB socket:


RS 232 C
9 -pin

The interface is electrically insulated fromall other circuits

## Ambient conditions

Variations due to ambient
temperature:
$\pm 0.1 \% / 10$ K
$0 \ldots 15 \ldots 30 \ldots 45^{\circ} \mathrm{C}$ (usage group II)
for temperature
Storage temperature
Annual mean
relative humidity
-40 to $+85^{\circ} \mathrm{C}$
$\leq 75 \%$

## Applicable standards and regulations

| IEC 688 or <br> DIN EN 60688 | Electrical measuring transducers for <br> converting AC electrical variables into <br> analogue and digital signals |
| :--- | :--- |
| IEC 1010 or <br> EN 61010 | Safety regulations for electrical measuring, <br> control and laboratory equipment |
| IEC 529 or <br> EN 60529 | Protection types by case (code IP) |
| IEC 255-4 Part E5 | High-frequency disturbance test <br> (static relays only) |
| IEC 1000-4-2/-3/-4/-6 | Electromagnetic compatibility for industrial- <br> process measurement and control <br> equipment |
| EN 55 011 | Electromagnetic compatibility of data <br> processing and telecommunication <br> equipment Limits and measuring principles <br> for radio interference and information <br> equipment |
| IEC 68-2-1/-2/-3/-6/-27 <br> or <br> EN 60 068-2-1/-2/-3/ <br> $-6 /-27$ | Ambient tests <br> -1 <br> -3 Cold, -2 Dry heat, <br> -37 Damp heat, -6 Vibration, |
| -27 Shock |  |

Safety
Protection class
Enclosure protection
Overvoltage category Insulation test (versus earth)

Surge test :
Test voltages

Ambient tests
EN 60 068-2-6
Acceleration frequency

Acceleration

II (protection isolated, EN 61 010-1)
IP 40, housing
IP 20, terminals
III
Input voltage: AC 400 V Input Current: AC 400 V RS 485: DC 40 V Power supply: AC 400 V DC 230 V
5 kV ; 1.2/50 ms; 0.5 Ws
$50 \mathrm{~Hz}, 1 \mathrm{~min}$. according to
EN 61 010-1
5550 V , inputs versus all other circuits as well as outer surface 3250 V , input circuits versus each other
3700 V, power supply versus RS 485 and SCl as well as outer surface $490 \mathrm{~V}, \mathrm{RS} 485$ versus SCl as well as outer surface

Vibration
$+2 \mathrm{~g}$
$3 \times 50 \mathrm{~g}$
3 shocks each in 6 directions
Cold, dry heat, damp heat

Installation data

Housing
drawings"
$:$ Housing material Lexan 940 (polycarbonate),
flammability class V-0 acc. to UL 94, self-extinguishing, non-dripping, free of halogen
For snapping onto top-hat rail ( 35 X 15 mm or 35 X 7.5 mm ) acc. to EN 50022
or
directly onto a wall or panel using the pull-out screw hole brackets Any
approx. 0.7 kg

Screw terminals with wire guards
$\leq 4.0 \mathrm{~mm}^{2}$ single wire or
$2 \times 2.5 \mathrm{~mm}^{2}$ fine wire

Table 2: RishDucer MXX, standard version
The versions of the transducer below programmed with the basic configuration are available ex stock. It is only necessary to quote the

| Description / Basic programming |  | Marking | Order No. |
| :---: | :---: | :---: | :---: |
| 1. Mechanical design: <br> 2. Rated input frequency: <br> 3. Power supply: | Housing T24 for rail and wall mounting 50 Hz $24 \ldots 60 \mathrm{~V} \text { DC, AC }$ | $\begin{aligned} & \text { M01-1 } \\ & 1 \\ & 7 \end{aligned}$ |  |
| 4. Power supply connection: <br> 5. Test certificate: <br> 6. Configuration: <br> See Table 4: "Ordering information" | 85... 230 V DC, AC <br> External connection (standard) <br> None supplied <br> Programmed basic configuration | $8$ |  |
| Basic configuration <br> 1. Application (system): <br> 2. Input voltage: <br> 3. Input current: <br> 4. Primary rating: <br> 5. Energy meter 1: <br> 6. Energy meter 2: <br> 7. Energy meter 3: <br> 8. Energy meter 4: <br> See Table 3: "Programming" | 4-wire, 3-phase system, asymmetric load <br> Design value $\mathrm{Ur}=400 \mathrm{~V}$ <br> Design value $\mathrm{Ir}=5 \mathrm{~A}$ <br> Without specification of primary rating <br> Not used <br> Not used <br> Not used <br> Not used | A 44 <br> U 21 <br> V 2 <br> W 0 <br> EA 00 <br> FA 00 <br> GA 00 <br> HA 00 |  |

Table 3: Programming

| Description / Basic programming | Application |  |  |
| :--- | :---: | :---: | :---: |
|  | A11 ... A16 | A34 | A24 / A44 |
| (system) <br> Single-phase AC |  |  |  |
| 3-wire, 3-phase symmetric load, phase-shift U: L1-L2, I: L1 * | A11 | - |  |
| 3-wire, 3-phase symmetric load | A 12 | - |  |
| 4-wire, 3-phase symmetric load | A 13 | - | - |
| 3-wire, 3-phase symmetric load, phase-shift U: L3-L1, I: L1 * | A 14 | - | - |
| 3-wire, 3-phase symmetric load, phase-shift U: L2-L3, I: L1 * | A15 | - | - |
| 3-wire, 3-phase asymmetric load | A16 | - | - |
| 4-wire, 3-phase asymmetric load | - | - |  |
| 4-wire, 3-phase asymmetric load, open-Y | - | A34 | - |

Table 3: Programming

| Description / Basic programming |  |  |  |  | Application |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  |  |  | A11 ... A16 | A34 | A24 / A44 |
| Rated value Ur $=57.7 \mathrm{~V}$ |  |  |  |  | U01 | - | - |
| Rated value Ur $=63.5 \mathrm{~V}$ |  |  |  |  | U02 | - | - |
| Rated value Ur $=100 \mathrm{~V}$ |  |  |  |  | U03 | - | - |
| Rated value Ur $=110 \mathrm{~V}$ |  |  |  |  | U04 | - | - |
| Rated value Ur $=120 \mathrm{~V}$ |  |  |  |  | U05 | - | - |
| Rated value Ur $=230 \mathrm{~V}$ |  |  |  |  | U06 | - | - |
| Rated value Ur |  |  |  | [V] | U91 | - | - |
| Rated value Ur $=100 \mathrm{~V}$ |  |  |  |  | U21 | U21 | U21 |
| Rated value Ur $=110 \mathrm{~V}$ |  |  |  |  | U22 | U22 | U22 |
| Rated value Ur $=115 \mathrm{~V}$ |  |  |  |  | U23 | U23 | U23 |
| Rated value Ur $=120 \mathrm{~V}$ |  |  |  |  | U24 | U24 | U24 |
| Rated value Ur $=400 \mathrm{~V}$ |  |  |  |  | U25 | U25 | U25 |
| Rated value Ur $=500 \mathrm{~V}$ |  |  |  |  | U26 | U26 | U26 |
| Rated value Ur [V] |  |  |  |  | U93 | U93 | U93 |
| Lines U01 to U06: Only for single phase AC current or 4-wire, 3-phase symmetric load |  |  |  |  |  |  |  |
| Line U91: Ur [V] 57 to 400 <br> Line U93: Ur [V] > 100 to 693 |  |  |  |  |  |  |  |
| Rated value $\mathrm{Ir}=1 \mathrm{~A}$ V1 |  |  |  |  | V1 | V1 |  |
| Rated value $\mathrm{Ir}=2 \mathrm{~A} \quad \mathrm{~V} 2$ |  |  |  |  | V2 | V2 |  |
| Rated value Ir $=5 \mathrm{~A}$ V3 |  |  |  |  | V3 | V3 |  |
| Rated value Ir > 1 to 6 |  |  |  | [A] | V9 | V9 | V9 |
| Without specification of primary rating |  |  |  |  | W0 | W0 | W0 |
| VT = | kV | $\checkmark$ | CT = |  | W9 | W9 | W9 |
| Line W9: Specify transformer ratio primary, e.g. $33 \mathrm{kV}, 1000 \mathrm{~A}$ <br>  The secondary ratings must correspond to the rated input <br>  voltage and current specified for feature 2, respectively 3. |  |  |  |  |  |  |  |
| Not used |  |  |  |  | EA00 | EA00 | EA00 |
| 11 | System |  | [Ah] |  | EA50 | EA51 |  |
| 11 | L1 |  | [Ah] |  | - | EA51 | EA51 |
| 12 | L2 |  | [Ah] |  | - | EA52 | EA52 |
| 13 | L3 |  | [Ah] |  | - | EA53 | EA53 |
| S | System |  | [VAh] |  | EA54 | EA54 | EA54 |
| S1 | L1 |  | [VAh] |  | - | - | EA55 |
| S2 | L2 |  | [VAh] |  | - | - | EA56 |
| S3 | L3 |  | [VAh] |  | - | - | EA57 |
| P | System | (incoming) | [Wh] |  | EA58 | EA58 | EA58 |
| P1 | L1 | (incoming) | [Wh] |  | - | - | EA59 |
| P2 | L2 | (incoming) | [Wh] |  | - | - | EA60 |
| P3 | L3 | (incoming) | [Wh] |  | - | - | Ea61 |

[^0]Table 3: Programming


## Electrical Connections

| Function |  | Connect. |
| :---: | :---: | :---: |
| Measuring input $\Theta$ | AC current IL1 | 1/3 |
|  | IL2 | 4 / 6 |
|  | IL3 | $7 / 9$ |
|  | AC voltage UL1 | 2 |
|  | UL2 | 5 |
|  | UL3 | 8 |
|  | N | 11 |
| $\begin{aligned} & \hline \text { RS } 485 \\ & \text { (MODBUS) } \end{aligned}$ | Tx + / Rx + | 23 |
|  | Tx-/ Rx- | 24 |
|  | GND | 25 |
|  | $\stackrel{\square}{\overline{=}}$ | 26 |
| Power supply$\rightarrow \bigcirc$ | AC | 13 |
|  | $\sim$ | 14 |
|  | DC + | 13 |
|  | - | 14 |

If power supply is taken from the measured voltage internal connections are as follows:

| Application (system) | Internal connection <br> Terminal / System |
| :--- | :---: |
| Single-phase AC current | $2 / 11 \quad$ (L1 - N) |
| 4-wire 3-phase <br> symmetric load | $2 / 11 \quad$ (L1 - N) |
| All other (apart from <br> A15 / A16 / A24) | $2 / 5 \quad$ (L1 - L2) |



## Electrical Connections



| Measuring inpu |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| System / application | Terminals |  |  |  |  |  |  |  |
| 3-wire <br> 3-phase symmetric <br> load <br> Phase-shift <br> U: L2 - L3 <br> I: L1 | Connect the voltage according to the following table for current measurement in L2 or L3: |  |  |  |  |  |  |  |
| 4-wire <br> 3-phase symmetric load I: L1 | Connect the voltage according to the following table for current measurement in L2 or L3: |  |  |  |  |  |  |  |
| 3-wire <br> 3-phase asymmetric load |  |  |  |  |  |  |  |  |

System / application

Relationship between PF, QF and LF


Fig. 3. Active power PF -_, reactive power QF -------, power factor LF -----

## Dimensional Drawing

All Dimensions are in mm


Fig. 5. RISH Ducer M01 in housing T24 clipped onto a top-hat rai ( $35 \times 15 \mathrm{~mm}$ or $35 \times 7.5 \mathrm{~mm}$, acc. to EN 50022 ).


Fig. 6. RISH Ducer M01 in housing T24, screw hole mounting brackets pulled out.

## Ordering Information (Table 5)

| DESCRIPTION | MARKING |
| :---: | :---: |
| 1. Mechanical design <br> Housing T24 for rail and wall mounting 01-1 | M |
| 2. Rated input frequency <br> 1) $50 \mathrm{~Hz}(60 \mathrm{~Hz}$ possible without additional error; $162 / 3 \mathrm{~Hz}$, additional error 1.25) <br> 2) $60 \mathrm{~Hz}(50 \mathrm{~Hz}$ possible without additional error; $162 / 3 \mathrm{~Hz}$, additional error 1.25) <br> 3) $162 / 3 \mathrm{~Hz}$ (not re-programming by user, $50 / 60 \mathrm{~Hz}$ possible, but with additional error 1.25) | 2 |
| 3. Power supply <br> 7) Nominal range $24 \ldots 60 \mathrm{~V}$ DC, AC | 7 |
| 4. Power supply connection <br> 1) External (standard) <br> 2) Internal from measuring input <br> Line 2: Not available for rated frequency $162 / 3 \mathrm{~Hz}$ and applications A15 / A16 / A24 (see Table 4) <br> Caution: The power supply voltage must agree with the input voltage (Table 4)! | 2 |
| 5. Test certificate <br> 0) None supplied <br> E) With test certificate in English | E |
| 6. Configuration <br> 0) Basic configuration, programmed <br> 9) Programmed acc. to specification <br> Line 0: Not available if the power supply is taken from the measuring input <br> Line 9: All the programming data must be entered on Form W 2408e and the form must be included with the order. | 9 |

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[^0]:    Continuation " 5 . Energy Meter 1 " see next page!

